

Scattering Delay Network: an Interactive Reverberator for Computer Games

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Motivation

Reverberators for computer games should:

- provide the best accuracy given...
- ...acceptable computational load (at least real-time)

Computational load

- Priority is always given to video performance
 - Not only powerful game workstations, but also slower architectures, e.g. handheld game consoles, ipods, mobile phones, etc..
-
- Provide explicit control of room properties (size, wall absorption...) to streamline game development
 - Scalable to different loudspeaker arrangements (2-channels, headphones, 5.1...)



Available reverberators

Many possibilities. Trade-off between complexity and accuracy:

DSP effects easy, fast, but inaccurate

Statistical very fast, but not directly related to room properties

FDN fast, but tuning is indirect and trial-and-error

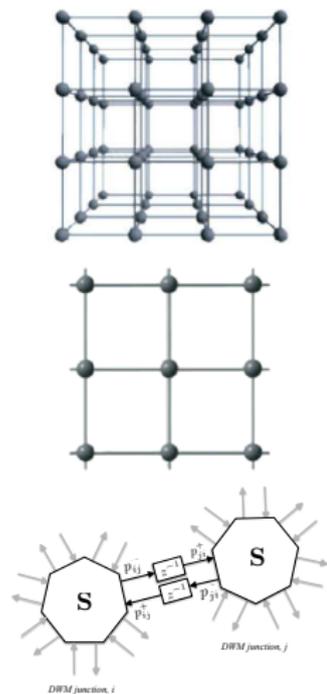
Synth. Reverb. fast, sounds good, but careful tuning of parameters

Conv. Reverb. sounds real, but require actual recordings

Ray Tracing accurate, but heavy load (especially for later parts of RIR, which is also the less important perceptually)

DWM wave equation solution, but heavy load (however, real-time implementation is possible with GPU)

Concepts of Digital Waveguide Mesh

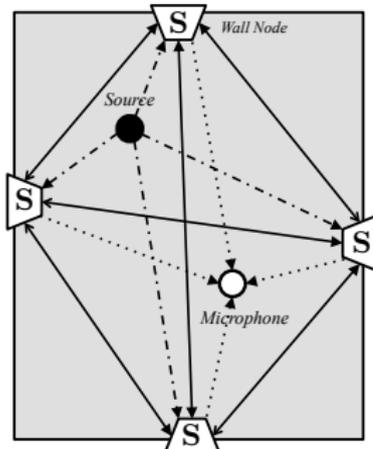


- The simulated space is sampled appropriately, each sampled point is a scattering junction
- Each junction is connected to its geometric neighbors through bidirectional lines
- Execution has two successive stages repeated at each time sample: scattering pass and propagation pass
- The outgoing waves to neighboring junctions $\mathbf{p}_i^-(n) = [p_{i,1}^-(n), \dots, p_{i,K}^-(n)]^T$ are obtained as: $\mathbf{p}_i^-(n) = \mathbf{S}\mathbf{p}_i^+(n)$ where $\mathbf{p}_i^+(n) = [p_{i,1}^+(n), \dots, p_{i,K}^+(n)]^T$ are the incoming wave variables
- $\mathbf{S} = \frac{2}{N-1} \mathbf{1}_{(N-1) \times (N-1)} - \mathbf{I}$
- If appropriate spatial sampling, equivalent to FTDT

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Design overview



2D room example

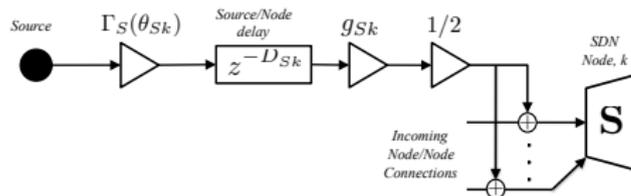
Scattering Delay Network

More importance to the parts of the RIR that are most significant perceptually: render correctly LOS and first-order reflections while approximating higher-order reflections with a single system.

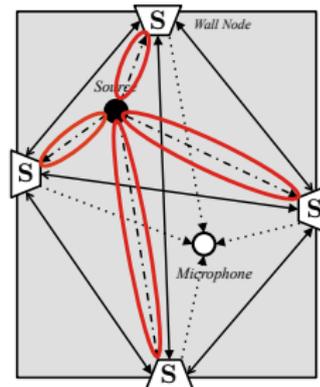
- Position the scattering nodes where the first-order reflections happen (in a ray-tracing sense)
- Mono-directional absorbing delay lines from the source to the scattering node
- Mono-directional absorbing delay lines from the scattering nodes to the microphone
- Bi-directional delay lines between the scattering nodes

Source to SDN connections

For each SDN node, structure as:



- Mono-directional delay line from the source to every SDN node
- Delay $D_{Sk} = \lfloor F_s \|\mathbf{x}_S - \mathbf{x}_k\| / c \rfloor$
- Attenuation $g_{Sk} = \frac{G}{\|\mathbf{x}_S - \mathbf{x}_k\|}$, $G \triangleq c / F_s$
- Weighted by the source directivity pattern



Pressure insertion

The output of the delay line is added to all the incoming lines p^+ of the SDN node

SDN Nodes

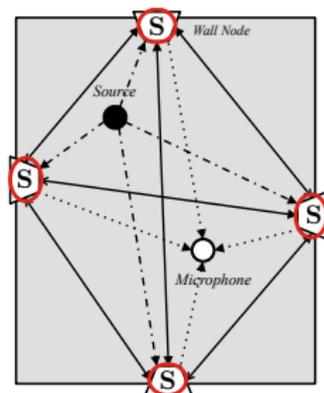
- Substantially a DWM node
- Wave arriving from a node propagates back to all the other nodes
- The outgoing wave variables $\mathbf{p}_i^-(n) = [p_{i,1}^-(n), \dots, p_{i,K}^-(n)]^T$ are obtained as:

$$\mathbf{p}_i^-(n) = \mathbf{S} \mathbf{p}_i^+(n)$$

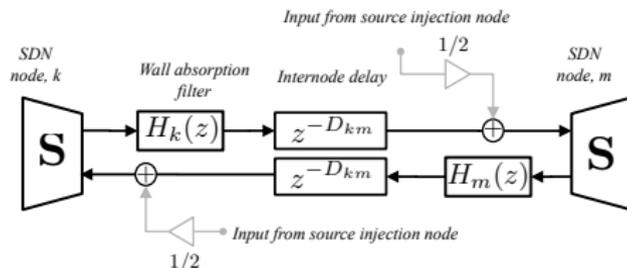
where $\mathbf{p}_i^+(n) = [p_{i,1}^+(n), \dots, p_{i,K}^+(n)]^T$ are the incoming wave variables

- The scattering matrix \mathbf{S} employed is the DWM lossless matrix:

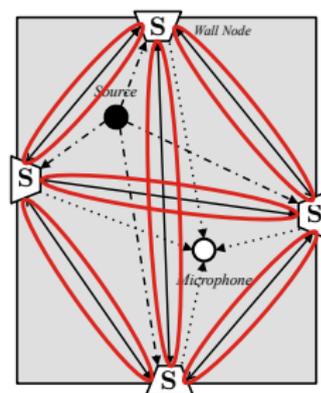
$$\mathbf{S} = \frac{2}{N-1} \mathbf{1}_{(N-1) \times (N-1)} - \mathbf{I}$$



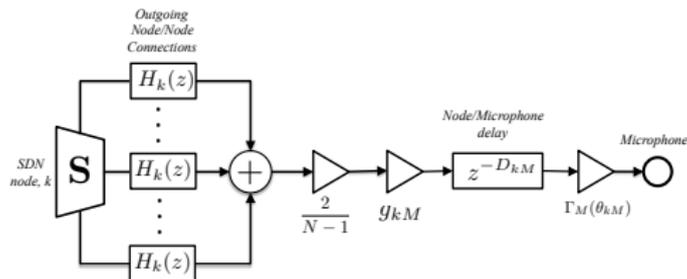
SDN interconnections



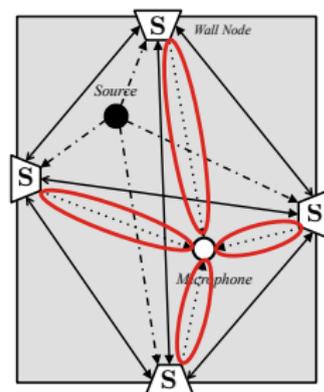
- Bi-directional delay line
- Delay $D_{km} = \lfloor F_s \|\mathbf{x}_k - \mathbf{x}_m\| / c \rfloor$
- No attenuation between SDN nodes
- Filters modeling wall absorption. Will be shown later that these filters can be set explicitly.
- The actual reverberator is formed by these lines + the SDN nodes



SDN node to microphone connections



- Attenuation $g_{kM} = 1 / \left(1 + \frac{\|\mathbf{x}_k - \mathbf{x}_M\|}{\|\mathbf{x}_S - \mathbf{x}_k\|} \right)$ such that $g_{S_k} g_{kM} = G / [\|\mathbf{x}_S - \mathbf{x}_k\| + \|\mathbf{x}_k - \mathbf{x}_M\|]$
- Weighted by the microphone directivity pattern



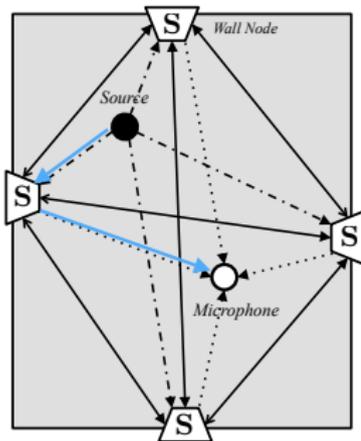
Pressure extraction

The input of the delay line is taken as the pressure (calculated after the wall filters) at the node as:

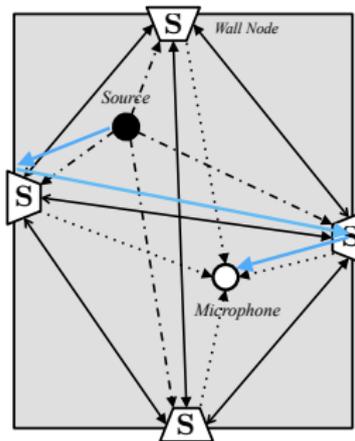
$$p_k(n) = \frac{2}{N-1} \sum_{i=1}^{N-1} \tilde{p}_{ki}^+(n)$$

Scattering Delay Network

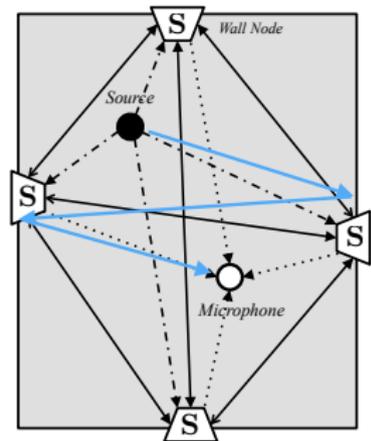
More importance to the parts of the RIR that are most significant perceptually: render correctly LOS and first-order reflections while approximating higher-order reflections with a single system.



I-order reflection



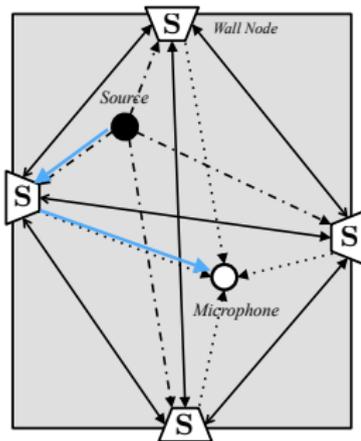
II-order reflection



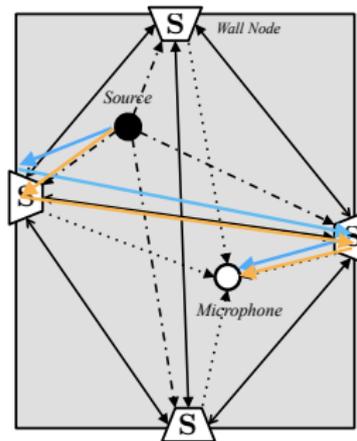
Another II-order reflection

Scattering Delay Network

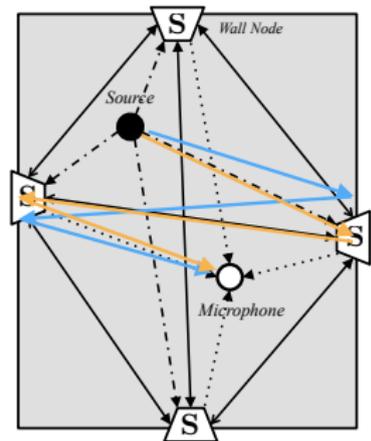
More importance to the parts of the RIR that are most significant perceptually: render correctly LOS and first-order reflections while approximating higher-order reflections with a single system.



I-order reflection

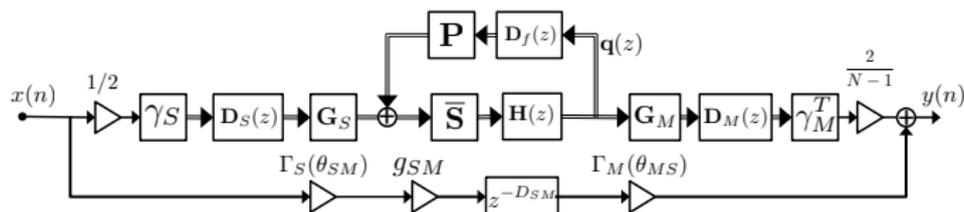


II-order reflection



Another II-order reflection

Transfer function



$$\gamma_S = [\Gamma_S(\theta_{S1}) \cdots \Gamma_S(\theta_{S1}), \Gamma_S(\theta_{S2}) \cdots \Gamma_S(\theta_{SN})]^T$$

$$\gamma_M = [\Gamma_M(\theta_{1M}) \cdots \Gamma_M(\theta_{1M}), \Gamma_M(\theta_{2M}) \cdots \Gamma_M(\theta_{NM})]^T$$

$$\mathbf{D}_S(z) = \text{diag}(z^{-D_{S1}} \cdots z^{-D_{S1}}, z^{-D_{S2}} \cdots z^{-D_{SN}})$$

$$\mathbf{D}_M(z) = \text{diag}(z^{-D_{M1}} \cdots z^{-D_{M1}}, z^{-D_{M2}} \cdots z^{-D_{MN}})$$

$$\mathbf{G}_S = \text{diag}(g_{S1} \cdots g_{S1}, g_{S2} \cdots g_{SN})$$

$$\mathbf{G}_M = \text{diag}(g_{M1} \cdots g_{M1}, g_{M2} \cdots g_{MN})$$

$$\bar{\mathbf{S}} = \text{diag}(\mathbf{S}, \mathbf{S}, \dots, \mathbf{S})$$

$$\mathbf{S} = \frac{2}{N-1} \mathbf{1}_{N-1 \times N-1} - \mathbf{I}$$

$$\mathbf{D}_f(z) = \text{diag}(z^{-D_{12}}, \dots, z^{-D_{NN-1}})$$

$$\mathbf{H}(z) = \text{diag}(H_1(z) \cdots H_1(z), H_2(z) \cdots H_N(z))$$

\mathbf{P} is a permutation matrix

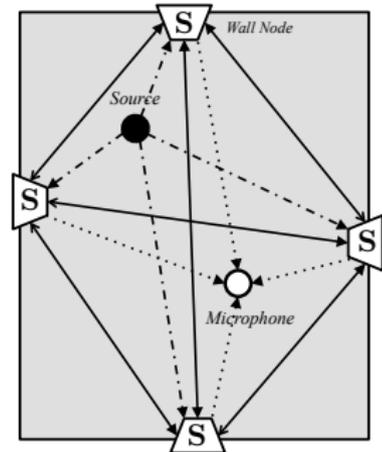
System's transfer function

$$H(z) = \bar{g} z^{-D_{SM}} + \frac{1}{N-1} \mathbf{k}_M(z) \left(\mathbf{H}(z^{-1}) - \bar{\mathbf{S}} \mathbf{P} \mathbf{D}_f(z) \right)^{-1} \bar{\mathbf{S}} \mathbf{k}_S(z),$$

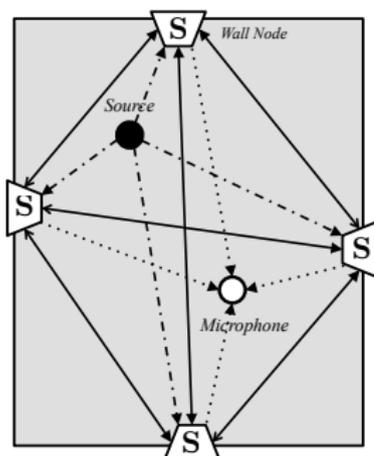
where $\mathbf{k}_M = \gamma_M^T \mathbf{D}_M \mathbf{G}_M$ and $\mathbf{k}_S = \mathbf{G}_S \mathbf{D}_S \gamma_S$.

Interactivity

- Source or microphone movement \Rightarrow position of SDN nodes is recalculated and delay line lengths are updated (removing/adding samples)
- Source or microphone turns \Rightarrow update in the directivity function Γ_S and Γ_M only.
- Changes in wall absorption characteristics or room dimensions can also be implemented.

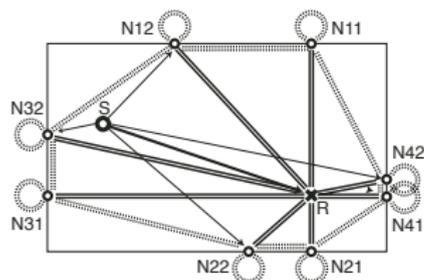


Recording Techniques



- Any microphone arrangement can be simulated. Intensity panning techniques (e.g. VBAP, sine pann. law..) or virtual coincident arrays (e.g. Ambisonics, HOA..) do not require duplication of the reverberator: multiple weighting Γ_M .
- Same for virtual binaural recording: Γ_M for each ear is an HRTF (both amplitude and delays).
- Non-coincident arrays, equivalent to multiple observation point \Rightarrow multiple SDNs. However, for near-coincident arrays, SDN nodes will be very close \Rightarrow the same SDN "backbone" can be shared, and only the microphone delay lines duplicated.

Relation to previous work



- Originally Digital Waveguide Networks were meant to be used as reverberators, but mainly used as complete room simulators
- One important follow-up:

M. Karjalainen *et al.* "Digital Waveguide Networks for Room Response Modeling and Synthesis," in *118th Conv. AES*, 2005.

DWN

Microphone is a scattering node
 Additional delay lines codirectional with room-axes
 Freq-dependent wall-filter modelled via self-connection at node (tuned heuristically)
 Attenuation on source-to-node and source-to-microphone attenuations only. Inaccurate 1-order reflections and problems with source close to wall.

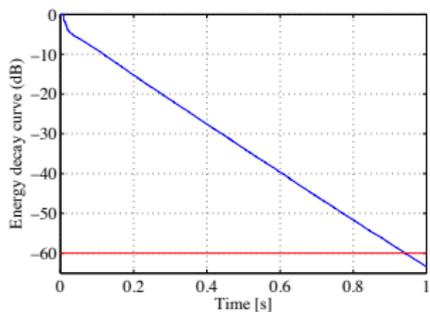
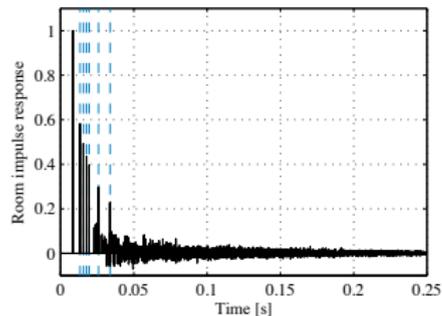
SDN

Microphone is passive element
 Not present (less accurate for low-freq room modes, but faster).
 Freq-dependent wall-filter modelled via explicit wall filters
 First-order reflections are correct by construction.

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Room Impulse Response (RIR) Example



Simulation setup

- Shoebox room 9x7x4m
 - Source in the center of the room
 - Microphone in $\mathbf{x}_M = [2, 2, 1.5]$
 - Frequency-independent absorption
 $\alpha = 0.2 \Rightarrow H_i(z) = \sqrt{1 - \alpha} = 0.89$
- Blue lines (theoretical 1-order reflections): correct by construction
 - Dense reverberation tail
 - Energy decay curve, $(\int_t^\infty |h(\tau)|^2 d\tau)$ is exponential (as for most real rooms). Thus scattering and attenuation by walls, microphone, and source lines provide realistic attenuation.
 - Reverberation time $RT_{60} \approx 0.94$.

Sabine and Eyring formulas

As a rough metric to assess the performance of the proposed method, comparison of the reverberation time of SDN with the two well-known empiric formulas:

Sabine formula

- First formula from empirical studies of 1910

$$T_{60} = \frac{0.161V}{\sum_i A_i \alpha_i}$$

where V is the room volume, A_i is the area of the i -th face, α_i is the absorption per square meter.

Eyring formula

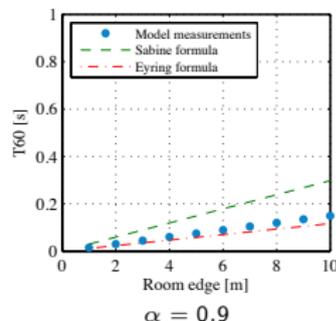
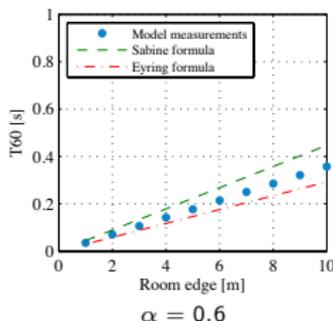
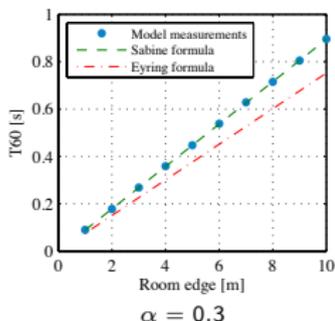
- Eyring modified Sabine formula because it yield $\alpha > 1$ for some acoustically dead rooms

$$T_{60} = -\frac{0.161V}{(\sum_i A_i) \log_{10} \left(1 - \frac{\sum_i A_i \alpha_i}{\sum_i A_i} \right)}$$

Results

Simulation setup

- Cubic room with edge x and uniform absorption $\alpha = 0.3, 0.6, 0.9$
- $\Rightarrow T_{60,Sab} = x \frac{0.161}{6\alpha}$ and $T_{60,Eyr} = x \frac{-0.161}{6 \log_{10}(1-\alpha)}$
- Source and microphone in the middle of the room (LOS removed)

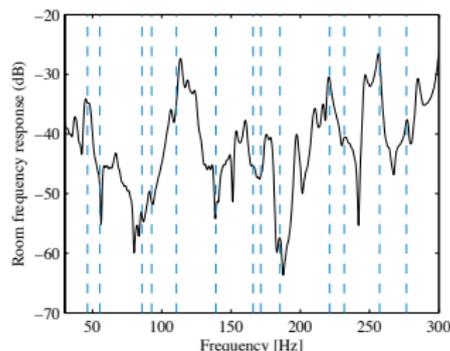


- Model's RT_{60} also increases linearly with x
- Always between the two formulas for all three absorption coefficient
- Model's RT_{60} get closer to Eyring formula prediction as absorption increases

Low frequency room modes

Room low-frequency modes

One of the main acoustical properties of rooms. The frequencies that result in resonance phenomena: $f_{n_x, n_y, n_z} = \frac{c}{2} \sqrt{\left(\frac{n_x}{l_x}\right)^2 + \left(\frac{n_y}{l_y}\right)^2 + \left(\frac{n_z}{l_z}\right)^2}$. Depending on the position of the source/observer, picks or dips in the frequency response.



Simulation setup

- Shoebox room 2x2.14x3.74m
- Source and microphone 1m away from one another around the centre of the room
- Frequency-independent $\alpha = 0.12$
- Axial modes (i.e. $f_{n_x, 0, 0}$, $f_{0, n_y, 0}$, and $f_{0, 0, n_z}$) are drawn in blue
- They correspond to peaks and dips in the Room Frequency Response

Frequency-dependent reverberation

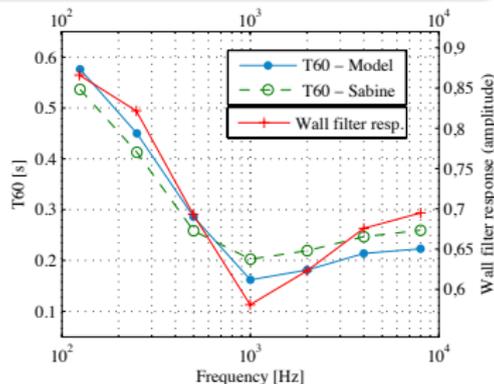
In FDN, filters are introduced to control frequency-dependent reverberation time. In SDN's the introduced filters model directly wall characteristics:

Simulation setup

- Cubic room 5x5x5m
- Source and microphone $\approx 3\text{m}$ away from one another around the centre
- All walls have frequency-dependent absorption (cotton carpet) implemented as a second-order IIR minimum-phase filter.

- Wall reponse as in figure (right axis)
- Reverberation time estimate through Sabine formula:

$$T_{60,Sab} = \frac{0.161V}{\sum_i A_i \alpha_i(\omega)} = \frac{0.161 \cdot 5}{6(1 - |H(e^{j\omega})|^2)}$$
- Very close match between RT_{60} produced by the model and Sabine formula's estimates \Rightarrow We are able to explicitly control wall properties



Conclusions

- A perceptual room simulator (reverberator) has been presented
- Room modelled by scattering nodes interconnected by bidirectional delay lines
- These SDN nodes are positioned where first-order reflections originate
- \Rightarrow First-order reflections are simulated correctly, while a rich but less accurate reverberation tail is obtained, consistent with the room characteristics.
- Transfer function was derived
- Examples and comparison with reverberation time formulas showed its performance
- Explicit control of wall acoustical properties